## User manual MB2-2F

## Frequency input: 0.01 Hz up 999.99 kHz

## Connection for NAMUR-, NPN-, PNP- and TTL-sensors



## Technical features:

- red display of -19999... 99999 digits
- red 55 points bargraph
- adjustable bar or dot operation or operation with permanent display of center point
- min/max memory
- display adjustment via frequency presetting or directly on the sensor signal
- 30 adjustable setpoints
- display flashing at threshold value exceedance/undercut
- Schmitt-Trigger-input
- zero-key for triggering of Hold, Tara
- permanent min/max-value recording
- digital frequency filter for contact bounce suppression and interference suppresion
- frequency filter with varying pulse control factor
- volume metering (totaliser) for frequencies up to 1 kHz (accurate to a pulse)
- mathematical function like reciprocal value, square root, rounding
- sliding averaging with an optional dynamic display filter
- setpoint generator
- brightness control
- programming interlock via access code
- protection class IP65 at the front side
- plug-in screw terminal
- sensor supply
- galvanic isolated digital input
- 2 relay output
- optional analog output
- optional: RS232 or RS485 interfaces
- accessories: PC-based configuration-kit PM-TOOL incl. CD \& USB adapter for devices without keypad and for a simple adjustment of standard devices.


## Identification

| STANDARD TYPES | ORDER NUMBER |
| :--- | :---: |
| Frequency |  |
| Housing size: $96 \times 96 \mathrm{~mm}$ | MB2-2FR5RR.0307.S72AD |
|  | MB2-2FR5RR.0307.W72AD |

## Options - breakdown of order code:



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## 1. Brief description

The panel meter instrument MB2-2F is a 5 -digit digital display with a 55 points bargraph display and two galvanic isolated setpoints; designed for pulse signals respectively 2 - and 3 -wire sensors. The configuration happens via four keys at the front. The integrated programming interlock prevents unrequested changes of parameters and can be unlocked again with an individual code. Optional the following functions are available: a supply for the sensor, a digital input for triggering of Hold (Tara), two analog outputs and interfaces for further evaluating in the unit. The electrical connection is done via plug-in terminals on the back side.
Selectable functions like e.g. the recall of the min/max-value, an averaging of the measuring signals, a nominal presetting or setpoint presetting, a direct threshold value regulation during operation mode and further measuring setpoints for linearisation, complete the modern device concept.

## 2. Assembly

Please read the Safety advices on page 37 before installation and keep this user manual for future reference.


1. After removing the fixing elements, insert the device.
2. Check the seal to make sure it fits securely.
3. Click the fixing elements back into place and tighten the clamping screws by hand. Then use a screwdriver to tighten them another half a turn.

CAUTION! The torque should not exceed 0.1 Nm !

Please state you favorite dimension symbol in your order, they can not be exchanged afterwards!

## 3. Electrical connection

Type MB2-2FR5RR.0307.S70AD with a supply of 100-240 VAC
Type MB2-2FR5RR.0307.W70AD with a supply of 10-40 VDC


## Attention!

For devices with sensor supply, terminal clamps 4 and 18, aswell as 3 and 19 are connected galvanically in the device.

MB2-2F-devices with a frequency input / pulse input


3-wire PNP


3-wire NPN


Namur


3-wire PNP


3-wire NPN


## 4. Description of function and operation

## Operation

The operation is divided into three different levels.

## Menu level (delivery status)

This level was designed for the standard settings of the device. Only menu items which are sufficent to set the device into operation are displayed. To get into the professional level, run through the menu level and parameterise PROF under menu item RUM.

Menu group level (complete function volume)
Suited for complex applications as e.g. linkage of alarms, setpoint treatment, totaliser function etc. In this level function groups which allow an extended parameterisation of the standard settings are availabe. To leave the menu group level, run through this level and parameterise ULOC under menu item RUM.

## Parameterisation level:

Parameter deposited in the menu item can here be parameterised. Functions, that can be changed or adjusted, are always signalised by a flashing of the display. Settings that are made in the parameterisation level are confirmed with [P] and thus saved. Pressing the [O]-key leads to a break-off of the value input and to a change into the menu level. All adjustments are saved automatically by the device and changes into operating mode, if no further key operation is done within the next 10 seconds.

| Level | Key | Description |
| :---: | :---: | :---: |
| Menu level | P | Change to parameterisation level and deposited values. |
|  | $\triangle \square$ | Keys for up and down navigation in the menu level. |
|  | 0 | Change into operation mode. |
| Parameterisation level | P | To confirm the changes made at the parameterization level. |
|  | $\triangle$ - | Adjustment of the value / the setting. |
|  | 0 | Change into menu level or break-off in value input. |
| Menu group level | P | Change to menu level. |
|  | $\triangle \square$ | Keys for up and down navigation in the menu group level. |
|  | O | Change into operation mode or back into menu level. |

## Funktion chart:



Underline:
(P) Takeover
$\Delta$ Value selection (+)
0 Stop Value selection (-)

### 4.1 Parameterisation software PM-TOOL:

Part of the PM-TOOL are the software on CD and an USB-cable with device adapter. The connection happens via a 4-pole micromatch-plug on the back side of the device, to the PC-side the connection happens via an USB plug.

System requirements: PC incl. USB interface
Software: Windows XP, Windows VISTA
With this tool the device configuration can be generated, omitted and saved on the PC. The parameters can be changed via the easy to handle program surface, whereat the operating mode and the possible selection options can be preset by the program.

## 5. Setting up the device

### 5.1. Switching-on

Once the installation is complete, start the device by applying the voltage supply. Before, check once again that all electrical connections are correct.

## Starting sequence

For 1 second during the switching-on process, the segment test ( 88888 ) is displayed, followed by an indication of the software type and, after that, also for 1 second, the software version. After the starting sequence, the device switches to operation/display mode.

### 5.2. Standard parameterisation: (flat operation level)

To parameterize the display, press the [P]-key in operating mode for 1 second. The display then changes to the menu level with the first menu item TYPE.




| Menü－Ebene | Parameter－Ebene |
| :---: | :---: |
|  | Selection of analog output，OUT．RR： <br> Default：4－20 <br> Three output signals are available： $0-10 \mathrm{VDC}, 0-20 \mathrm{~mA}$ and $4-20 \mathrm{~mA}$ ，with this function，the demanded signal is selected． |
| BLEEK | Setting up the final value of the analog output，OUT．EM： <br> Default： 10000 <br> The final value is adjusted from the smallest digit to the highest digit with［ $\mathbf{A}$ ］［ $\mathbf{V}$ ］and digit by digit confirmed with［P］．A minus sign can only be parameterised on the highest digit．After the last digit，the device changes back into menu level． |
|  | Setting up the initial value of the analog output，out．OF： <br> Default： 00000 <br> The final value is adjusted from the smallest digit to the highest digit with［ $\mathbf{\Delta}$ ］［ $\mathbf{V}$ ］and digit by digit confirmed with［P］．A minus sign can only be parametrised on the highest digit．After the last digit，the device changes back into menu level． |
| $\begin{array}{l\|l\|l\|} \hline L & i-i \\ \nabla & \Delta \end{array}$ | Threshold values／limit values，$L /-1$ ： <br> Default： 2000 <br> For both limit values，two different values can be parameterized．With this，the parameters for each limit value are called up one after another． |
| $\begin{aligned} & H \Xi-! \\ & \|\nabla \Delta\| \end{aligned}$ | Hysteresis for limit values， HY － ： <br> Default： 00000 <br> The delayed reaction of the alarm is the difference to the threshold value，which is defined by the hysteresis． |


| Menu level | Parameterisation level |
| :---: | :---: |
|  | Function if display falls below / exceeds limit value, FU-l: <br> Default: HIGH <br> H ILH <br> Laus <br> The limit value undercut can be selected with LOUU (LOW = lower limit value) and limit value exceedance can be selected with HIGH (HIGH = upper limit value). If e.g. limit value 1 is on a switching threshold of 100 and occupied with function „HIGH", the alarm will be activated by reaching the threshold. If the limit value is allocated to "LOW", an alarm will be activated by undercut of the threshold. See page 29. |
|  | Threshold values / limit values, Ll-Z: <br> Default: 3000 <br> For both limit values, two different values can be parameterized. With this, the parameters for each limit value are called up one after another. |
| $\begin{aligned} & H ப-\Sigma \mid \\ & \|\nabla \Delta\| \end{aligned}$ | Hysteresis for limit values, HY -ट: <br> Default: 00000 <br> The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis. |
| $\begin{aligned} & \mid F \omega-\Sigma \\ & \uparrow \nabla \Delta \mid \end{aligned}$ | Function if display falls below / exceeds limit value, $\mathrm{FU}-\mathrm{z}$ : <br> Default: HIGH <br> The limit value undercut can be selected with LOUU (LOW = lower limit value) and limit value exceedance can be selected with $\operatorname{HIGH}$ (HIGH = upper limit value). If e.g. limit value 1 is on a switching threshold of 100 and occupied with function HIGH, the alarm will be activated by reaching the threshold. If the limit value is allocated to LOU, an alarm will be activated by undercut of the threshold. |
| $\begin{aligned} & \text { LLGdE } \\ & \|\nabla \Delta\| \mid \end{aligned}$ | User code (4-digit number-combination, free available), U.CODE: <br> Default: 0000 <br> If this code is set ( $>0000$ ), all parameters are locked, if $L O C$ has been selected before under menu item RUH. By pushing [P] during operation mode for approx. 3 seconds, CODE appears in the display. To get to the unlocked reduced parameter, the user needs to enter the preset U.CODE. This code has to be entered before each parameterisation, until the R.CODE (master code) unlocks all parameters again. |

Menu level

### 5.4. Extended parameterisation (Professional operation level)

### 5.4.1. Signal input parameters



| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \text { LUFE } \\ & \|\nabla \Delta\| \end{aligned}$ | Selection of the input signal, TYPE: <br> Default: FREGU $5 E n 5 . F \frac{\Delta}{\nabla} F r E A \Delta \frac{\Delta}{\nabla} P$ <br> If the scaling of the device is done via SEM5.F (Sensor calibration), the frequency range needs to be preset under RRMGE and is adjusted by application of the final value/initial value. If FREQU (factory calibration) is preferred, the final value needs to be entered under EMD and the final frequency needs to be entered under EMDR. Under OFFS the initial value needs to be entered and under OFFSA the initial frequency. There is no application of the measuring signal. Confirm the selection with [P] and the display switches back to menu level. |
| $\begin{aligned} & -\boldsymbol{R}\|\underline{\square}\| \\ & \nabla \Delta \mid \end{aligned}$ | Setting the end value of the measuring range, EMD: <br> Default: 100E3 <br> Choose between six different frequency ranges. Confirm the selection with [P] and the display switches back to menu level. |
| $\begin{aligned} & \square E \square \square \\ & \nabla \Delta \end{aligned}$ | Setting the final value of the measuring range, EMD: Default: 10000 <br> Set the final value from the smallest to the highest digit with [ $\mathbf{A}$ ] [ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level. If SEMS was selected as input option, you can only select between MOCR and CRL. With MOCR, only the previously set display value is taken over, and with CRL, the device takes over both the display value and the analogue input value. |



| Menu level | Parameterisation level |
| :---: | :---: |
| GELRコ $\square$ $\|\nabla \Delta\|$ | Setting of the pulse delay, DELRY: <br> Default: 0 <br> With the impulse delay of $0-250$ seconds (max), frequencies can be collected, that are even smaller than by the predetermined measuring time of the device. If e.g. a delay of 250 seconds is set, this means that the device waits up to 250 seconds for an edge, before it assumes a 0 Hz frequency. Thus frequencies up to 0.004 Hz can be collected. |
|  | Adjustment of the optimum digital frequency filter, FI.FRQ: <br> Default: MO <br> If the optional filter is not activated by the adjustment MD, frequences are ignored by the adjusted frequency filter. Act on the assumption that the pulse-duty factor is 1:1. Accordingly the minimal pulse duration is derived from the half of the time of oscillation. Use a filter of 10 Hz or 20 Hz for contact bounce suppression. |
| $F \text { i.r } R L$ $\square$ $\|\nabla \Delta\|$ | Adjustment of the pulse-duty factor at activated digital filter, FI.RRT: Default: l-1 <br> Adjustment of the desired pulse-duty factor for pulse duration and pulse interruption. Like this, a special pulse behaviour can be adjusted. |
|  | Setting up the tare/offset value, TRRA: <br> Default: 0 <br> The given value is added to the linerarized value. In this way, the characteristic line can be shifted by the selected amount. |
|  | Number of additional setpoints, SPCT: <br> Default: 00 $\square$ <br> 1 $\square$ $\square$ $\square$ <br> 30 additional setpoints can be defined to the initial- and final value, so linear sensor values are not linearised. Only activated setpoint parameters are displayed. |


| Menu level | Parameterisation level |
| :---: | :---: |
|  | Display values for setpoints, D15.01 ... D15.30: <br> Under this parameter setpoints are defined according to their value. At the sensor calibration, like at final value/offset, one is asked at the end if a calibration shall be activated. |
|  | Analog values for setpoints, IMP. 01 ... IMP.30: <br> These setpoints are displayed at works setting ( $4-20 \mathrm{~mA}$ ) only. Here, demanded analog values can be choosen freely. The input of steadily rising analog values needs to be done selfcontained. |
|  | Display underflow, DIUMD: <br> Default: -19999 <br> With this function the device undercut ( $\qquad$ ) can be defined on a definite value. Exception is input type 4-20 $\mathbf{m A}$, it already shows undercut at a signal $<1 \mathrm{~mA}$, so a sensor failure is marked. |
|  | Display overflow, DIDUE: <br> Default: 99999 |
|  | Input variable of process value, SIG.IN: <br> Default: R.MERS <br> RHERS $\qquad$ ก. L 5 $\square$ <br> With this parameter the device can be controlled via the analog input signals R.MERS = SEMS.F / FRESU or via the digital signals of the interface M.BUS = RS232/RS485 (modbus protocol). With $[P]$ the selection is confirmed and the device changes into menu level. |
| $\begin{aligned} & r E L \\ & \|\nabla \Delta\| \end{aligned}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level . -IMP-". |

### 5.4.2. General device parameters




| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \boxed{5 L E P} \\ & \|\nabla \Delta\| \end{aligned}$ | Dynamic for the sliding average determination，STEP： <br> Default：MO <br> With STEP the sliding average determination can be adjusted dynamically．If 6 pro or 12 pro was selected，a frequency value with a variance of $6 \%$ or $12 \%$ of the current display value is taken over directly for the sliding averaging．The display appears to be more dynamic at a fast frequency change，without appearing disturbed by a slightly unsteady frequency． |
| $\begin{aligned} & \square E \square \square \\ & \nabla \square \square \end{aligned}$ | Zero point slowdown，ZERO： <br> Default： 00 <br> At the zero point slowdown，a value range around the zero point can be preset，so the display shows a zero．If e．g．a 10 is set，the display would show a zero in the value range from－10 to +10 ；below continue with -11 and beyond with +11 ．The maximum adjustable range of value is 99. |
|  | Definite contstant value，CONST： <br> Default： 0 <br> The constant value can be evaluated via the alarms or via the analog output，like the current measurand．The decimal place cannot be changed for this value and is taken over by the current measurand．Like this a setpoint generator can be realised via the analog output by this value．Furthermore it can be used for calculating the difference．At this the constant value is substracted from the current measurand and the difference is evaluated in the alerting or by the analog output．Thus regulations can be displayed quite easily． |
| $\begin{aligned} & \square \square \pi .71 \\ & \nabla \Delta \Delta \mid \end{aligned}$ | Minimum constant value，COM．M： <br> Default：－19999 <br> The minimum constant value is adjusted from the smallest to the highest digit with the navigation keys［ $\mathbf{A}$ ］［ $\mathbf{\nabla}$ ］and confirmed digit per digit with［P］．A minus sign can only be adjusted on the highest digit．After the last digit the display changes back into menu level． |
| ■ar.クロ | Maximum constant value，CON．MR： <br> Default： 99999 <br> The maximum constant value is adjusted from the smallest to the highest digit with the navigation keys［ $\mathbf{\Delta}$ ］［ $\mathbf{\nabla}$ ］and confirmed digit per digit with［P］．A minus sign can only be adjusted on the highest digit．After the last digit the display changes back into menu level． |

Menu level
Menu level

| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \operatorname{LRSL.4} \\ & \|\nabla \Delta\| \end{aligned}$ | Special function [0]-key, TRST.4: <br> Default: MO <br> For the operation mode, special functions can be deposited on the [O]-key. This function is activated by pressing the key. With TRRR the device is set temporarily on a parameterised value. The device acknowledges the correct taring with showing 00000 in the display. SET.TR adds a defined value on to the currently displayed value. Via TOTAL the current value of the totaliser can be displayed for approx. 7 seconds, after this the device switches back on the parameterised display value. If TOT.RE was deposited, the totaliser can be set back by pressing the navigation keys [ $\mathbf{A}$ ] [ $\mathbf{V}$ ], the device acknowledges this with showing 00000 in the display. EHT.RE deletes the min/max-memory. If $H O L D$ has been selected, the moment can be hold constant by pressing the [O]-key and is updated by releasing the key. Advice: HOLD is activated only, if HOLD was selected under parameter DISPL. RCTUR shows the measuring value for approx. 7 seconds, after this the device switches back on the parameterised display value. The same goes for $R V G$, here the sliding average values will be displayed. The constant value COMST can be recalled via the digital input, or changed digit per digit. At RL-I.. RL-4 an output can be set and therewith e.g. a setpoint adjustment can be done. If $M O$ is selected, the [O]-key is without any function in the operation mode. |
|  | Special function digital input, DIG.IM: <br> Default: MO <br> In operation mode, the above shown parameters can be laid on the optional digital input, too. Function description see TRST.Y. |
| $\begin{aligned} & \square\|E E\| \\ & \|\nabla \Delta\| \end{aligned}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level ..-FCT-". |

### 5.4.3. Bargraph functions



| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \text { GR.SI } \\ & \|\nabla \Delta\| \end{aligned}$ | Bargraph, BR.5RC: <br> Default: RCTUR <br> With this function the following values can be allocated to the display: the current measurand, the min/max value, the totaliser value, the process-controlled hold value, the sliding average value, the constant value or the difference between constant and current value of the bargraph. With [P] the selection is confirmed and the device changes into menu level. |
| BREno $\|\nabla \Delta\|$ | Adjusting the final value of the bargraph, BR.EMD: <br> Default: 10000 <br> Set the final value from the smallest to the highest digit with [ $\mathbf{A}$ ] [ $\mathbf{V}$ ] and confirm each digit with [P]. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level. |
| $\begin{aligned} & \square \boldsymbol{B I F} \\ & \sqrt{\nabla} \mid \end{aligned}$ | Adjusting the initial value of the bargraph, BR.OFF: <br> Default: 0 <br> Set the initial value from the smallest to the highest digit with [ $\mathbf{\Delta}$ ] [ $\mathbf{V}$ ] and confirm each digit with $[\mathrm{P}]$. A minus sign can only be parameterized on the highest value digit. After the last digit, the display switches back to the menu level. |
| $\begin{aligned} & \square B F \square L \\ & \nabla \nabla \Delta \end{aligned}$ | Selection of the bargraph functions, BR.FCT: <br> Default: BRR.FO <br> The bargraph can be displayed with the following possibilites: bars forwards, bars backwards, bars from the middle, a dot display of the bargraph or a dot display with a permanently displayed midpoint. Confirm the selection by pressing the [P] button. The display then switches back to the menu level again. |

Menu level

### 5.4.4. Safety parameters



| Menu level | Parameterisation level |
| :---: | :---: |
|  | Setting up the user code, U.CODE: <br> Default: 0000 <br> Via this code, reduced sets of parameters OUT.LE and RL.LEV can be unlocked, in case of a locked programming. There is no access to further parameters via this code. The U.CODE can only be changed via the correct input of the R.CODE (master code). |
| $\begin{aligned} & \text { R.LadE } \\ & \|\nabla \Delta\| \end{aligned}$ | Master code, R.CODE: <br> Default: 1234 <br> By entering $8 . \operatorname{CODE}$ the device will be unlocked and all parameters are released. |
| BuLELE | Release/lock analog output parameter, oUT.LE: Default: RLL <br> Analog output parameter can be locked or released for the user: <br> - EM-OF: the initial or final value can be changed in operation mode <br> - OUT.ED: the output signal can be changed from e.g. 0-20 mA to $4-20 \mathrm{~mA}$ or $0-10$ VDC <br> - RLL: analog output parameters are released <br> - MO: all analog output parameters are locked |
| $\begin{aligned} & \text { FLLEEU } \\ & \overbrace{\nabla} \Delta \mid \end{aligned}$ | Release/lock alarm parameters, RL.LEU: <br> Default: RLL <br> กロ <br> LIML <br> RLIRIL <br> RLL <br> This parameter describes the user release/user lock of the alarm: <br> - LIMIT: here only the range of value of the threshold values 1-4 can be changed <br> - RLRM.L: here the range of value and the alarm trigger can be changed <br> - RLL: all alarm parameters are released <br> - MO: all alarm parameters are locked |


| Menu level |  | Parameterisation level |
| :--- | :--- | :--- |
|  | - | $\Sigma$ |

### 5.4.5. Serial parameters




## 5．4．6．Analog output parameters



| Menu level | Parameterisation level |
| :---: | :---: |
|  | Selection reference of analog output，OUTPT： <br> Default：RCTUR <br> The analog output signal can refer to different functions，in detail these are the current measurand，the min－value，the max－value，the totaliser function／sum function，the constant value or the difference between current measurand and constant value．If HOLD was selected， the signal of the analog output will be kept．It can be continued processing after a deactivation of HOLD．With［P］the selection is confirmed and the device changes into menu level． |
| $\begin{aligned} & \text { BuL. }-B \\ & \|\nabla \Delta\| \end{aligned}$ | Selection analog output，OUT．RR： <br> Default：4－20 $\square \square-I \square \frac{\Delta}{\nabla} \square-\Omega \square \frac{\Delta}{\nabla} \square 4-2 \square \frac{\Delta}{\nabla}$ <br> Three output signals are available：0－10 VDC，0－20 mA and 4－20 mA．Select the demanded signal with this function． |
|  | Setting the final value of the analog output，OUT．EM： <br> Default： 10000 <br> The final value is adjusted from the smallest to the highest digit with［ $\mathbf{\Delta}$ ］［ $\mathbf{V}$ ］and confirmed digit per digit with［P］．A minus sign can only be parameterised on the highest digit．After the last digit the device changes back into menu level． |
| $\begin{gathered} \text { HぃL.ロF } \\ \|\nabla \Delta\| \end{gathered}$ | Setting the initial value of the analog output，out．OF： <br> Default： 00000 <br> The initial value is adjusted from the smallest to the highest digit with［ $\mathbf{\Delta}$ ］［ $\mathbf{V}$ ］and confirmed digit per digit with［P］．A minus sign can only be parameterised on the highest digit．After the last digit the device changes back into menu level． |


| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \square F L \square U \\ & \|\nabla \Delta\| \end{aligned}$ | Overflow behaviour, O.FLOU: <br> Default: EDGE <br> To recognise and evaluate faulty signals, e.g. by a controller, the overflow behaviour of the analog output can be defined. As overflow can be seen either EDGE, that means the analog output runs on the set limits e.g. 4 and 20 mA , or T0.0FF (input value smaller than initial value, analog output switches on e.g. 4 mA ), TO.END (higher than final value, analog output switches on e.g. 20 mA ). If TO.MIM or TO.MRX is set, the analog output switches on the smallest or highest possible binary value. This means that values of e.g. $0 \mathrm{~mA}, 0 \mathrm{VDC}$ or values higher than 20 mA or 10 VDC can be reached. With [P] the selection is confirmed and the device changes into menu level. |
| $\begin{aligned} & \mid r E L \\ & \|\nabla \Delta\| \end{aligned}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level ..-OUT-". |

### 5.4.7. Relay functions




| Menu level | Parameterisation level |  |  |
| :---: | :---: | :---: | :---: |
| $\uparrow \nabla \Delta$ | Alarm relay <br> Default：RL－z <br> LoLl <br> Each setpoin at activated available in th other selecte activated／dea front of the de | REL－2： <br> optional）can be linke rms RL－1／4 or deactiv menu level LOG－1 and unctions，these two p vated，in this case the ce．With［P］the selec | RL－n：．．．．RL－n4 |
| $\begin{aligned} & \operatorname{LQE}-己 \\ & \|\nabla \Delta\| \end{aligned}$ | Logic relay 2 <br> Default：OR <br> Here，the sw describes the | LOG－2 <br> nar <br> ching behaviour of | ay is defined via a logic link，the following schema RL－l and RL－2． |
|  | $\square 1$ | $A 1 \vee A 2$ | As soon as a selected alarm is activated，the relay operates．Equates to operating current principle． |
|  | nロr | $\overline{A 1 \vee A 2}=\overline{A 1} \wedge \overline{A 2}$ | The relay operates only，if no selected alarm is active．Equates to quiescent current principle． |
|  | 日n | $\mathrm{A} 1 \wedge \mathrm{a} 2$ | The relay operates only，if all selected alarms are active． |
|  | の日ワ | $\overline{A 1 \wedge A 2}=\overline{A 1} \vee \overline{A 2}$ | As soon as a selected alarm is not activated，the relay operates． |
|  | With［P］the selection is confirmed and the device changes into menu level． |  |  |
|  | Alarms for r Default： 8.2 <br> R．$i$ <br> The allocatio alarms can b <br> ［P］the select | ay 2 ，com－z： <br> R．？ <br> of the alarms to rela chosen．This parame n is confirmed and the | happens via this parameter，one alarm or a group of is only available if $L O G I C$ was selected under REL－I．With vice changes into menu level． |
| $\begin{aligned} & \square \mid E L \\ & \uparrow \nabla \Delta \mid \end{aligned}$ | Back to men <br> With $[P]$ the | group level，RET： <br> ection is confirmed an | he device changes into menu group level ．．－REL－＂． |

### 5.4.8. Alarm parameters



| Menu level | Parameterisation level |
| :---: | :---: |
| BLTI | Dependency alarm 1, RLRM. 1 : <br> Default: actur <br> The dependency of alarm 1 can be related to special functions, in detail these are the current measuring value, the min-value, the max-value, the totaliser value/sum-value, the constant value or the difference between the current measurand and the constant value. If HOLD was selected, then the alarm is hold and processed just after deactivation of HOLD. EHTER causes the dependency either by pressing the [O]-key on the front of the housing or by an external signal via the digital input. With $[P]$ the selection is confirmed and the device changes into menu level. <br> Example: <br> By using the maximum value RLRRM. $1=$ MAX.VR in combination with a threshold monitoring $F U-7=H H G H$, an alarm confirmation can be realised. Use the navigation keys, the 4th key or the digital input for confirmation. |
| $\begin{aligned} & \begin{array}{l\|l\|} \hline L & I \\ \hline \nabla & \Delta \end{array} \\ & \nabla \end{aligned}$ | Threshold values / limit values, $\mathrm{L}-\mathrm{T}$ : <br> Default: 2000 <br> The limit value defines the threshold, that activates/deactivates an alarm. |
| $\begin{aligned} & H U-i \\ & \|\nabla \Delta\| \end{aligned}$ | Hysteresis for threshold values, Hy -7: <br> Default: 00000 <br> The delayed reaction of the alarm is the difference to the threshold value, which is defined by the hysteresis. |


| Menu level | Parameterisation level |
| :---: | :---: |
| $\begin{aligned} & \mid F_{\boldsymbol{L}}-i \\ & \|\nabla \Delta\| \end{aligned}$ | Function for threshold value undercut/exceedance, $\mathrm{FU}-\mathrm{i}$ : <br> Default: HIGH <br> A limit value undercut is selected with LOUU (for LOW = lower limit value), a limit value exceedance with HIGH (for HIGH = higher limit value). If e.g. limit value 1 is on a threshold leve of 100 and allocated with function HIGH, an alarm is activated by reaching the threshold level. If the threshold value was allocated to LOW, an alarm will be activated by undercutting the threshold value, as long as the hysteresis is zero. |
| $\begin{aligned} & \text { Lan-i } \\ & \|\nabla \Delta\| \end{aligned}$ | Switching-on delay, TOM-7: <br> Default: 000 $\begin{array}{lllllll} \boldsymbol{1} & P & \boxed{1} & P & \boxed{\square} & \Delta & \square \end{array}$ <br> For limit value 1 one can preset a delayed switching-on of 0-100 seconds. |
| $\begin{aligned} & E \square F-i \\ & \|\nabla \Delta\| \end{aligned}$ | Switching-off delay, TOF-7: <br> Default: 000 <br> For limit value 1 one can preset a delayed switching-off of 0-100 seconds. |
| $\begin{aligned} & \square \\ & \hline-E L \\ & \nabla \nabla \Delta \mid \end{aligned}$ | Back to menu group level, RET: <br> With [P] the selection is confirmed and the device changes into menu group level ..-RLI-". |

The same applies for RL己 to RLB.

### 5.4.9. Totaliser (Volume metering)



| Menu level | Parameterisation level |
| :--- | :--- | :--- |
| Totaliser state, ToTAL: |  |
| Default: 0 FF |  |


| Menu level | Parameterisation level |
| :--- | :--- | :--- |

## Programming interlock:



## 6. Reset to default values

To return the unit to a defined basic state, a reset can be carried out to the default values.
The following procedure should be used:

- Switch off the power supply
- Press button [P]
- Switch on voltage supply and press [P]-button until „-----" is shown in the display. With reset, the default values of the program table are loaded and used for subsequent operation. This puts the unit back to the state in which it was supplied.


## Caution! All application-related data are lost.

## 7. Alarms / Relays

This device has 4 virtual alarms that can monitor one limit value in regard of an undercut or exceedance. Each alarm can be allocated to an optional relay output S1-S2; furthermore alarms can be controlled by events like e.g. hold value or min/max-value.

| Function principle of alarms / relays |  |
| :--- | :--- |
| Alarm / Relay $\mathbf{x}$ | Deactivated, instantaneous value, min/max-value, hold value, <br> totaliser value, sliding average value, constant value, difference <br> between instantaneous value and constant value or an activation <br> via the digital input |
| Switching threshold | Threshold / limit value of the change-over |
| Hysteresis | Broadness of the window between the switching thresholds |
| Working principle | Operating current / Quiescent current |



## Operating current

By operating current the alarm S1-S2 is off below the threshold and on on reaching the threshold.

## Quiescent current

By quiescent current the alarm S1-S2 is on below the threshold and switched off on reaching the threshold.

## Switching-on delay

The switching-on delay is activated via an alarm and e.g. switched 10 seconds after reaching the switching threshold, a shortterm exceedance of the switching value does not cause an alarm, respectively does not cause a switching operation of the relay. The switching-off delay operates in the same way, keeps the alarm / the relay switched longer for the parameterised time.

## 8. Interfaces

## Connection RS232

Digital device M3 PC - 9-pole Sub-D-plug

| 14 | RxD | TxD | 3 |
| :--- | :--- | :--- | :--- |
| 15 | TxD |  |  |
| 16 | GND | RxD | 2 |
|  |  |  |  |
|  |  |  |  |

## Connection RS485

Digital device M3


The interface RS485 is connected via a screened data line with twisted wires (Twisted-Pair). On each end of the bus segment a termination of the bus lines needs to be connected. This is neccessary to ensure a secure data transfer to the bus. For this a resistance (120 Ohm) is interposed between the lines Data B (+) and Data A (-).

## 9．Programmer examples

## Examples：Adjustment according to number of sprockets at unknown rotation speed．

－nearly $100 \%$ of the rotation speeds are in the range of 0 to 30.000 r．p．m．
－the number of sprockets varies（without gearing）between 1 and 100
－in automation，the frequency supply never exceeds 10 kHz （rather 3 kHz ）
Assume a rotation speed of 60 r．p．m．at 1 Hz ，whereat the real frequency value will not be considered．

Our example complies with a number of sprockets of 64 ．

## Setting up the advice

Based on the default settings of the display，the following parameters need to be changed：

| Parameter | Settings | Description |
| :---: | :---: | :---: |
| $L \square P E$ | FrEM | Applying of the measuring signal is not applicable． |
| －RのEE | 153 | Complies with 9.9999 Hz |
| End | 5 | Assumed final value |
| EndR | DRSLU | Complies with 64 sprockets |

If the frequency needs to be displayed with a position after decimal point，then a 60 has to be selected as final value for this adjustment．

| Parameter | Settings | Description |
| :---: | :---: | :---: |
| L $\square_{\text {IV }}$ | FrEGu | Applying of the measuring signal is not applicable． |
| $\rightarrow \boldsymbol{R}$ | 153 | Complies with 9.9999 Hz |
| Ena | $\square \square$ | Assumed final value |
| 日ロL | $\square$ | 1 position after decimal point |
| Enar | 7， 015 | Complies with 64 sprockets |

## Example：Rotation speed of a machine shaft

There are 4 sprockets on one machine shaft．Applied in an angle of $90^{\circ}$ to each other and to the rotation speed measurement．The sprockets are collected via a proximity switch and evaluated by the frequency device，which shall display the rotation speed in $\mathrm{U} / \mathrm{min} .0 \ldots 3600 \mathrm{U} / \mathrm{min}$ is preset as rotation speed range of the machine．

## Calculation of the input frequency

| Number of sprockets | $=4$ |
| :--- | :--- |
| Rotation speed | $=3600 \mathrm{U} / \mathrm{min}$ |

$$
\begin{aligned}
& \text { Final rotation speed }\left[\frac{U}{\min }\right] \\
& \text { Final frequency }[\mathrm{Hz}]=\frac{60\left[\frac{s}{\min }\right] \times 1 U}{3600 \frac{U}{\min }} \times 4=240 \mathrm{~Hz} \\
& \text { Final frequency }[\mathrm{Hz}]=\frac{30 \frac{s}{\min } \times 1 U}{}
\end{aligned}
$$

## Setting up the device

Based on the default settings of the device，following parameters need to be changed：

| Parameter | Settings | Description |
| :---: | :---: | :---: |
| L $-\boldsymbol{F}$ | $F \underline{F G G 4}$ | As the input frequency is known，the device does not need to be applied to the measuring section． |
| －RッEE | CREG | The final frequency is in the range of 100.00 to 999.99 Hz ． |
| Ena | コロロロ | A rotation speed of 3600 shall be displayed as final value． |
| Eかの回 | こ4 | The final frequency for display value 3600 is 24.00 Hz ． |

## 10. Technical data

| Panel meter housing |  |
| :---: | :---: |
| Dimensions | 96x96x56 mm (BxHxD) |
|  | 96x96x82 mm (BxHxD) incl. plug-in terminal |
| Panel cut-out | $91.0^{+0.6} \times 91.0^{+0.6} \mathrm{~mm}$ |
| Wall thickness | up to 10 mm |
| Fixing | Screw elements |
| Material | LEXAN 500R, black |
| Sealing material | EPDM, 65 Shore, black |
| Protection class | Standard IP65 (front), IP00 (back side) |
| Weight | approx. 330 g |
| Connection | plug-in terminal; wire-cross section up to $2.5 \mathrm{~mm}^{2}$ |
| Display |  |
| Display height | 14 mm |
| Segment colour | red |
| Display range | -19999 to 99999 |
| Setpoints | one LED per setpoint |
| Overflow | horizontal bars at the top |
| Underflow | horizontal bars at the top |
| Display time | 0.1 up to 10.0 seconds |
| Bargraph | 55 segments in $270^{\circ}$ angle |
| Bragraph colour | red |
| Input |  |
| Transmitter | Namur, 3-wire initiator, impulse input, TTL |
| High/Low level TTL level | $\begin{aligned} & >15 \mathrm{~V} /<4 \mathrm{~V}-\operatorname{Uin} \max .30 \mathrm{~V} \\ & >4,6 \mathrm{~V} /<1,9 \mathrm{~V} \end{aligned}$ |
| Input frequency | 0.01 - 999.99 kHz |
| Input resistance | $\mathrm{R}_{1}$ at $24 \mathrm{~V} / 4 \mathrm{k} \Omega / \mathrm{R}_{1}$ at Namur $1,8 \mathrm{k} \Omega$ |
| Frequency filter | none, $100 \mathrm{~Hz}, 50 \mathrm{~Hz}, 20 \mathrm{~Hz}, 10, \mathrm{~Hz}, 5 \mathrm{~Hz}, 2 \mathrm{~Hz}$ |
| Accuracy |  |
| Temperature drift | $50 \mathrm{ppm} / \mathrm{K}$ |
| Measuring time | $0.1 \ldots 10.0$ seconds, respectively optional impulse delay of 250 seconds |
| Measuring error | $0.05 \%$ of measuring range $\pm 1$ digit |
| Resolution | approx. 19 bit per measuring range |


| Output |  |
| :---: | :---: |
| Sensor supply | $24 \mathrm{VDC} / 50 \mathrm{~mA}$; $12 \mathrm{VDC} / 50 \mathrm{~mA}$; $5 \mathrm{VDC} / 20 \mathrm{~mA}$ |
| Analog output | 0/4-20 mA / burden $350 \Omega$ or 0-10 VDC / $10 \mathrm{kOhm}, 16$ bit |
| Switching output |  |
| Relay with change-over contact Switching cycles | 250 VAC / 5 AAC; 30 VDC / 5 ADC <br> $30 \times 10^{3}$ at $5 \mathrm{AAC}, 5 \mathrm{ADC}$ ohm resistive burden <br> $10 \times 10^{6}$ mechanically <br> Division according to DIN EN50178 / <br> Characteristics accrording to DIN EN60255 |
| Interface |  |
| Protocol | Modbus with ASCII or RTU-protocol |
| RS232 | 9.600 Baud, no parity, 8 Databit, 1 Stopbit, wire length max. 3 m |
| RS485 | 9.600 Baud, no parity, 8 Databit, 1 Stopbit, wire length max. 1000 m |
| Power supply | 100-240 VAC $50 / 60 \mathrm{~Hz}, \mathrm{DC} \pm 10 \%$, max. 15 VA 10-40 VDC; 18-30 VAC $50 / 60 \mathrm{~Hz}$, max. 15 VA |
| Memory | EEPROM |
| Data life | $\geq 100$ years at $25^{\circ} \mathrm{C}$ |
| Ambient conditions |  |
| Working temperature | $0^{\circ} \ldots 50^{\circ} \mathrm{C}$ for panel meters, $-20^{\circ} \ldots 60^{\circ} \mathrm{C}$ for built-on devices |
| Storing temperature | $-20 \ldots 80^{\circ} \mathrm{C}$ |
| Weathering resistance | relative humidity 0-80\% on years average without dew |
| Height | up to 2000 m above sea level |
| EMV | EN 61326 |
| CE-sign | Conformity according to directive 2004/108/EG |
| Safety standard | Accroding to low voltage directive 2006/95/EG EN 61010; EN 60664-1 |

## 11. Safety advices

Please read the following safety advices and the assembly chapter 1 before installation and keep it for future reference.

## Proper use

The MB2-2F-device is designed for the evaluation and display of sensor signals.


## Danger! Careless use or improper operation can result in

 personal injury and/or cause damage to the equipment.
## Control of the device

The panel meters are checked before dispatch and sent out in perfect condition. Should there be any visible damage, we recommend close examination of the packaging. Please inform the supplier immediately of any damage.

## Installation

The MB2-2F-device must be installed by a suitably qualified specialist (e.g. with a qualification in industrial electronics).

## Notes on installation

- There must be no magnetic or electric fields in the vicinity of the device, e.g. due to transformers, mobile phones or electrostatic discharge.
- The fuse rating of the supply voltage should not exceed a value of 0.5 A N.B. fuse!
- Do not install inductive consumers (relays, solenoid valves etc.) near the device and suppress any interference with the aid of RC spark extinguishing combinations or free-wheeling diodes.
- Keep input, output and supply lines separate from one another and do not lay them parallel with each other. Position "go" and "return lines" next to one another. Where possible use twisted pair. So, you receive best measuring results.
- Screen off and twist sensor lines. Do not lay current-carrying lines in the vicinity. Connect the screening on one side on a suitable potential equaliser (normally signal ground).
- The device is not suitable for installation in areas where there is a risk of explosion.
- Any electrical connection deviating from the connection diagram can endanger human life and/or can destroy the equipment.
- The terminal area of the devices is part of the service. Here electrostatic discharge needs to be avoided. Attention! High voltages can cause dangerous body currents.
- Galvanic isolated potentials within one complex need to be placed on a appropriate point (normally earth or machines ground). So, a lower disturbance sensibility against impacted energy can be reached and dangerous potentials, that can occur on long lines or due to faulty wiring, can be avoided.


## 12. Error elimination

|  | Error description | Measures |
| :---: | :---: | :---: |
| 1. | The device shows a permanent overflow | - The input frequency is too high for the selected frequency range. Correct RAMGE according to this. <br> - Disturbing pulses lead to an increased input frequency, activate FI.FRQ at smaller frequencies or shield the senor line. <br> - A mechanic switching contact chatters. Activate the frequency filter FI.FRQ with 10 or 20 kHz . <br> - The display was taught faulty under TYPE = SEMS.F. Error elimination see below. |
| 2. | The device shows a permanent underflow. | - An offset frequency OFF5R bigger than 0 Hz respectively a „living zero" was selected, in which no frequency is aligned. Check the sensor lines or set the OFFSR onto 0 Hz . <br> - The display underflow DL.UMD was selected too high. The accroding parameter needs to be adapted. <br> - The device was taught faulty under TYPE = SEM5.F. Error elimination see below. |
| 3. | The displayed values switches sporadical. | - Disturbances lead to short-term display switches. For smaller frequences use the frequency filter FI.FRQ, select a higher measuring time or use the sliding averaging. <br> - The sprockets that needs to becollected, are not evenly spread on a shaft or are not measured really exact. Use the sliding averaging RVG if necessary with the dynamic function STEP. The displayed value DISPL needs to be set on RVG. |
| 4. | The display remains on zero. | - The sensor was not connected properly. Check the connection lines and if necessary the sensor supply. Best directly on the screw terminals of the device! <br> - A PNP- respectively NPN-output does not reach the required threshold. Check the voltage between terminal 2 and 3 with a Multimeter. Depending on signal form it generally shoud be between 4 V and 15 V . The thresholds can be checked more safely with an oscilloscope. If necessary include an external pull-up or pull-down. <br> - A Namur-sensor does not react. Check the distance between the sensor and the sprocket / survey mark and if necessary measure the voltage between 1 and 3. In open condition the input voltage needs to be smaller than $2,2 \mathrm{~V}$ sein and in active condition bigger than $4,6 \mathrm{~V}$. <br> - The selected range of the input frequency is too high. Reduce the frequency range RAMGE to a smaller value. <br> - The activated frequency filter FI.FRQ suppresses the relevant pulses. Increase the filter frequency FI.FRQ or use the adaption of the key proportion FI.RRT. If this should not work, temporarily deactivate the frequency filter with $\operatorname{FI} . F R Q=M O$. <br> - The device was taught faulty under TYPE = SEMS.F. Change into TYPE FREQU and preset the assumed frequency range RAMGE and the according initial and final values EMD, OFFS, EMDA, and OFFSA. So you can check if a frequency signal was connected to the input. |
| 5. | The device shows HELP in the 7 -segment display | - The device located an error in the configuration memory, excecute a reset to the default values and set up the device according to your application. |
| 6. | Program numbers for the parameterisation of the input are not available | - The programming interlock is activated. <br> - Enter correct code. |
| 7. | The device shows ERRI in the 7 -segment display | - Contact the manufacturer if errors of this kind occur. |
| 8. | The device does not react as expected. | - If you are not sure, that the device has been parameterised before, restore the state of delivery as described in chapter 6. |

